

Evolving Scrapyard: Integrating new solutions for advanced scrap management

Marcelo Saparrat
Tecnoap

tecnoap
VISIÓN HOLÍSTICA

SCRAPYARD[®]
by tecnoap

Context

Raw materials account for **70%** of steel production costs. Scrap is the largest portion of these costs.

- Consequences of poor scrap management and classify:



Overcost on scrap



Lack of traceability and stock control.



Possible fraud scenarios in scrap metal procurement.



Complex audit process.



Low efficiency of the melting process.



Discrepancies between different stocks, accounting and other areas.



Possible conflict with scrap suppliers due to the inherent subjectivity of the reception process.



Impact on the quality of the steel produced.

Objectives, Features of the solution



- Digitization of the scrap incoming scrap workflow



- Automatic scrap classify



- Volumetric calculation of the truck box
- Truck weight capture



- Density determination



- Integration of scrap chemistry
- Integration with Manufacturing Execution System (MES) & ERP (SAP)
- **Detection of truck container.**



- **Hazardous objects detection.**

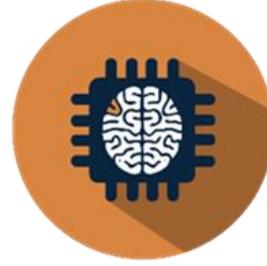


- **Scrap characterization.**

Technical approach, Technologies



Cloud



Artificial intelligence



Big Data

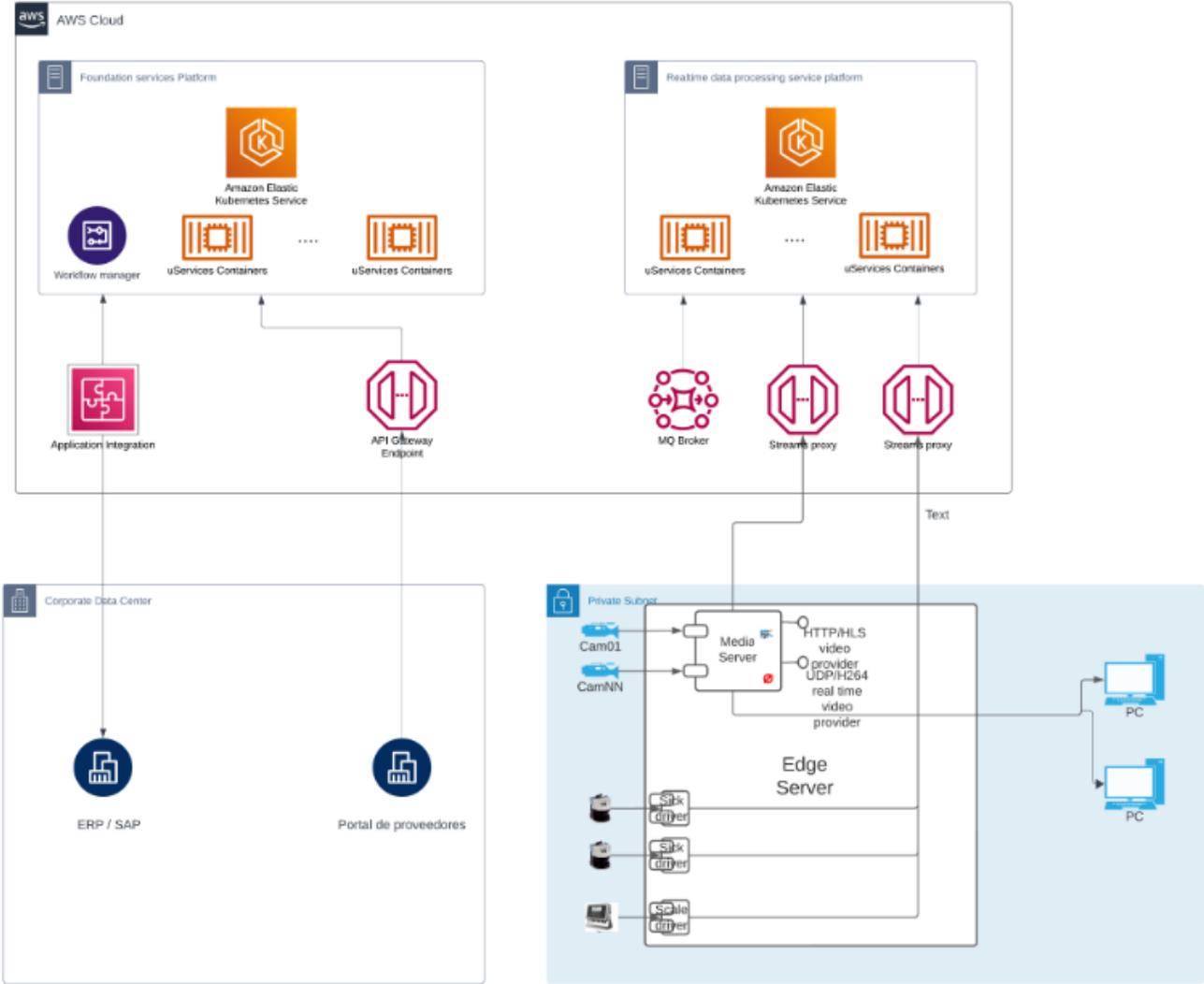


Internet of things

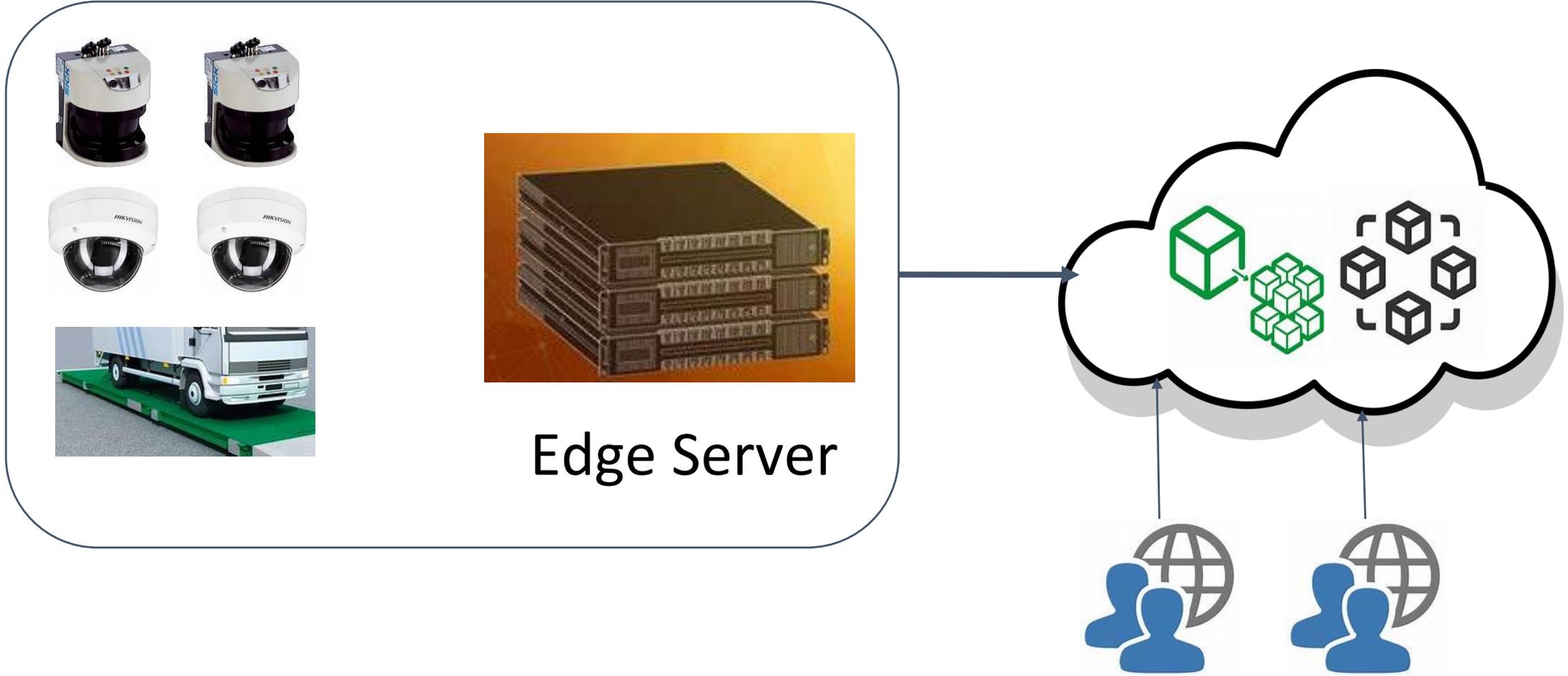


Software

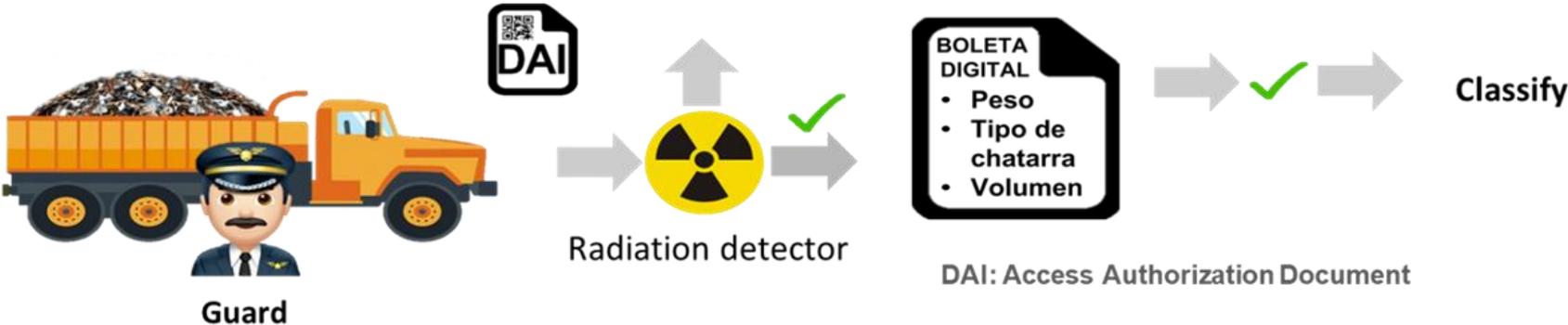
Full cloud/edge based implementation



Full cloud/edge based implementation



Integration



This section highlights various technologies used in the integration process:

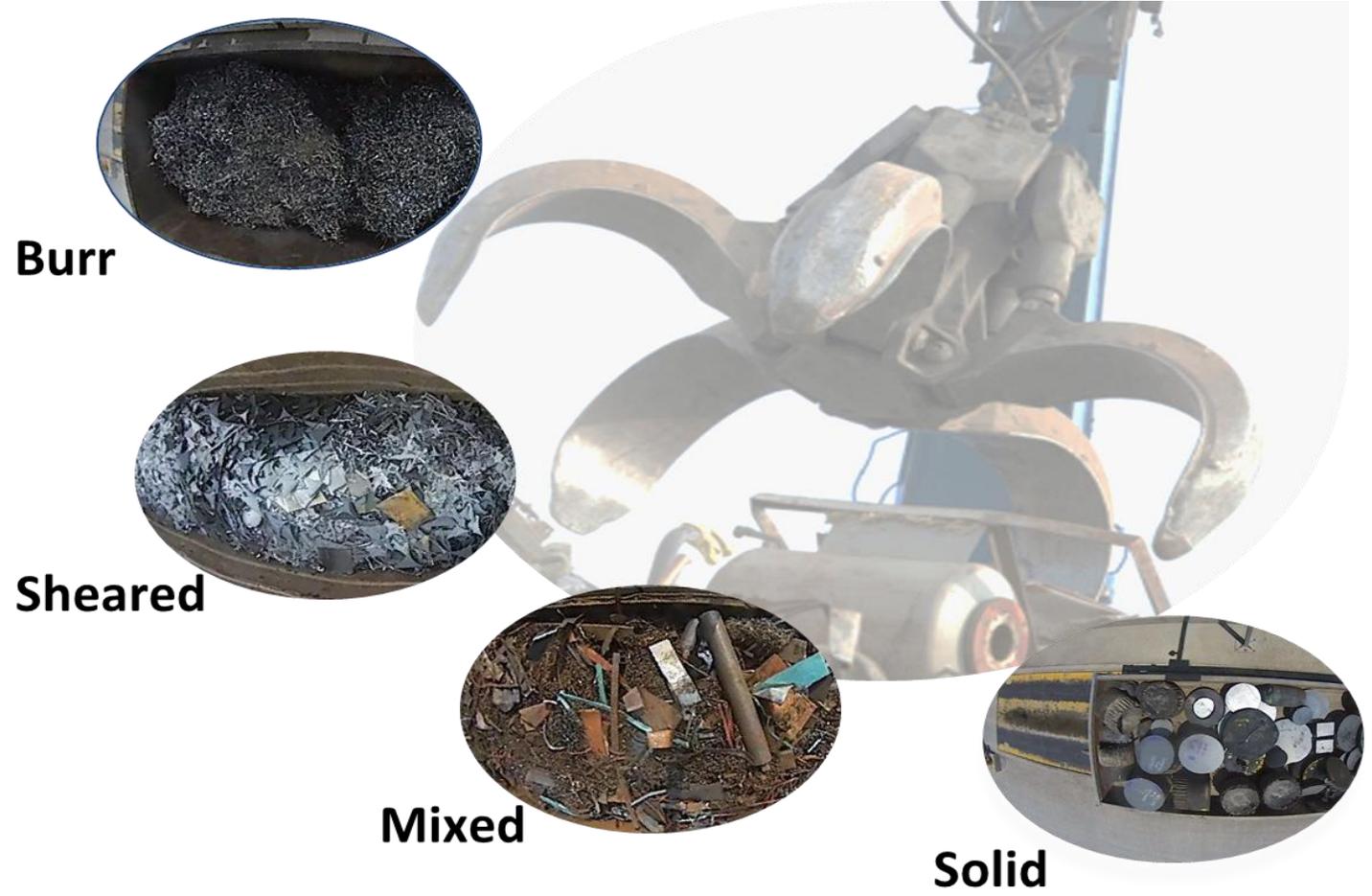
- QR reader**: Represented by a QR code icon.
- Integration Scale**: Represented by a scale icon.
- TECHNOLOGIES**: Represented by a stylized head icon with circuitry.
- Classification by AI**: Represented by a dome camera icon.
- Volumetric calculation**: Represented by a LIDAR sensor icon projecting a red cone.

LIDAR Technology (Light Detection And Ranging)

Field implementation



Examples of scrap metal



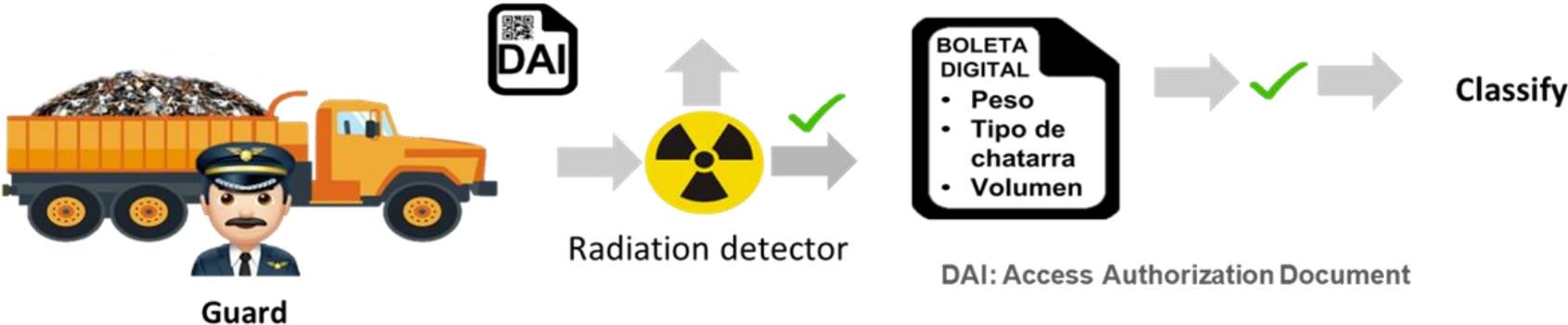
Burr

Sheared

Mixed

Solid

Pre-Classification



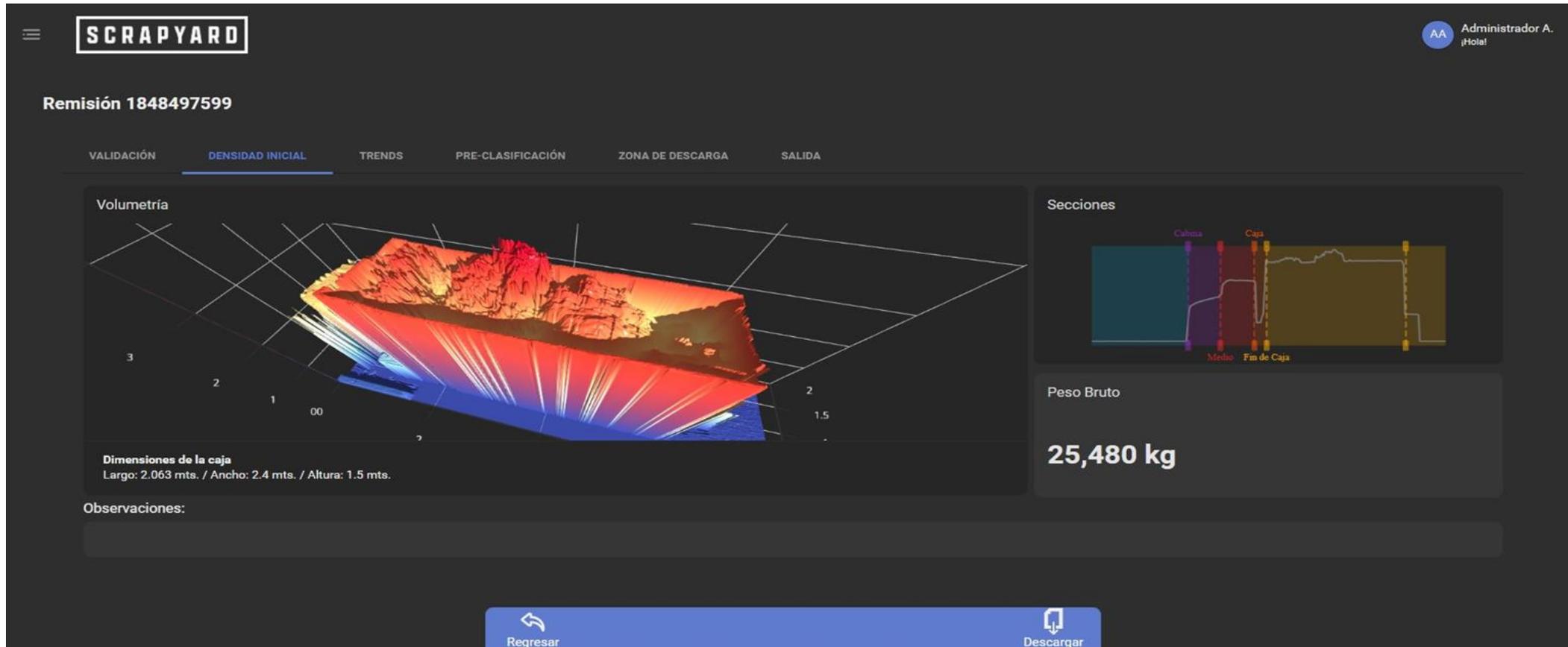
Pre-Classification screen, entrance area

The screenshot displays the 'Pre-Clasificación' (Pre-Classification) interface. At the top, a navigation bar includes 'VALIDACIÓN', 'DENSIDAD INICIAL', 'TRENDS', 'PRE-CLASIFICACIÓN' (active), 'ZONA DE DESCARGA', and 'SALIDA'. The user is identified as 'Administrador A.' with a 'Hola!' greeting.

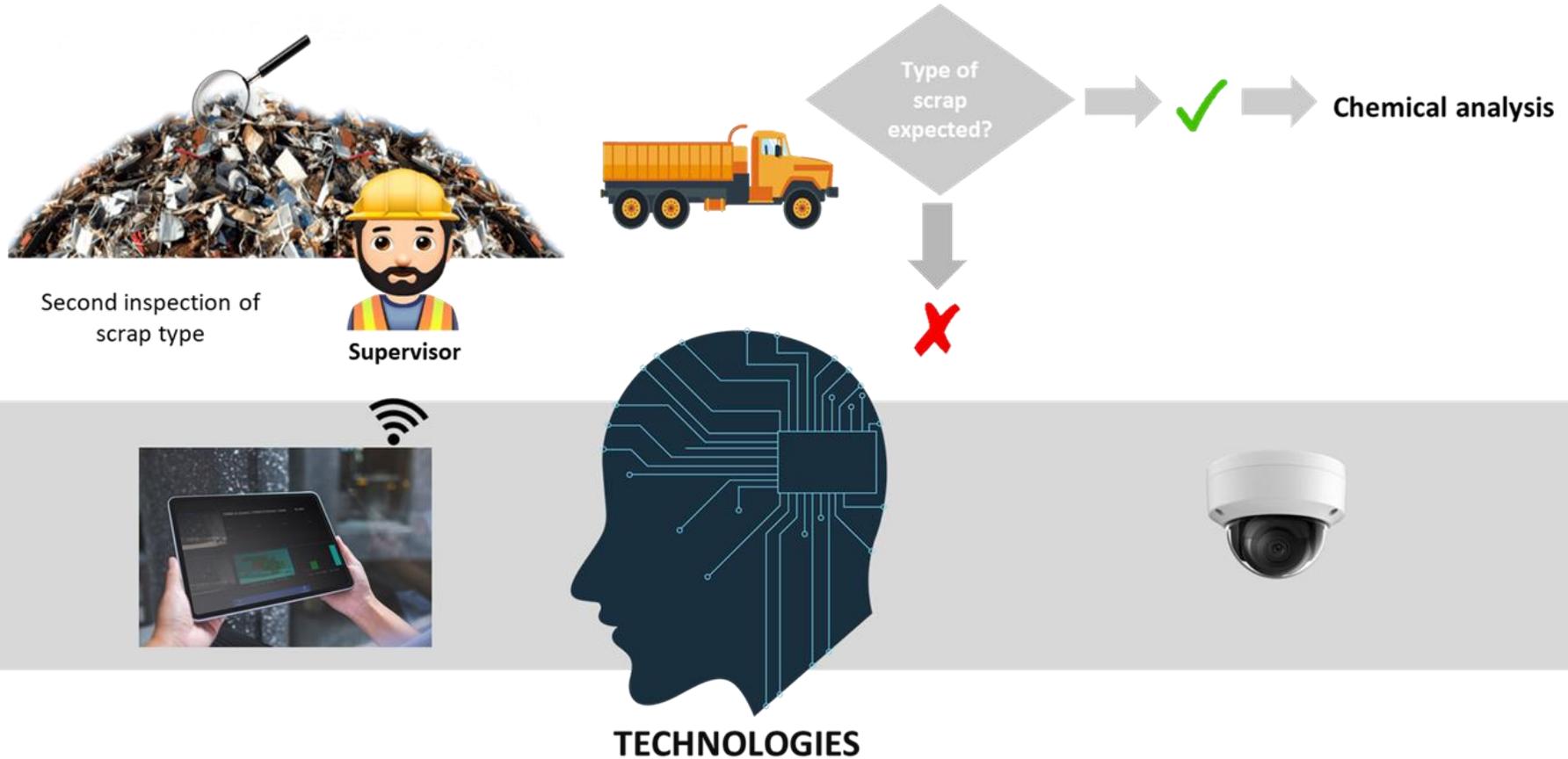
The main content area is divided into several sections:

- Imagen Capturada:** A camera feed from a scale ('Báscula') showing scrap metal. A green bounding box highlights the scrap, and a timestamp '11:04:44' is visible in the bottom right corner.
- Remisión:** CHNA23 (SOLIDO)
- Usuario:** CHNA23 (SOLIDO)
- Detectado:** MIXTO
- Grado de confianza:** 100.00%
- Cizalla:** 0.00%
- Rebaba:** 0.00%
- Sólido:** 0.00%
- Vacío:** 0.00%
- Observaciones:** CHNA23
- Homogeneidad:** A grid of images showing the distribution of scrap, with a legend below: cizalla (red), mixto (green), rebaba (yellow), solido (blue), vacío (cyan).
- Distribución:** A bar chart showing the distribution of scrap types. The 'mixto' category (green) is the dominant one, reaching nearly 100%.
- Mayor Coincidencia:** mixto

Volume and density calculation



Classification, uploading area



Classification, uploading area



Classification screen

The screenshot displays the SCRAPYARD classification interface. At the top left, there is a menu icon and the SCRAPYARD logo. The top right corner shows the user 'Administrador A.' with a 'Hola!' greeting. The main content area is divided into several sections:

- Imagen Capturada:** A photograph of a pile of scrap metal with a timestamp of 15:50:44.
- Remisión:** CHNA14 (MIXTO)
- Usuario:** CHNA14 (MIXTO)
- Detectado:** CIZALLA
- Grado de confianza:** 100.00%
- Rebaba:** 0.00%
- Mixto:** 0.00%
- Sólido:** 0.00%
- Vacío:** 0.00%
- Observaciones:** CHNA14
- Homogeneidad:** A horizontal bar chart showing the distribution of categories: cizalla (red), mixto (green), rebaba (yellow), solido (blue), and vacío (cyan).
- Distribución:** A vertical bar chart showing the percentage distribution of categories: cizalla (red, ~85%), mixto (green, 0%), rebaba (yellow, 0%), solido (blue, ~15%), and vacío (cyan, 0%).
- Mayor Coincidencia:** cizalla

At the bottom, there are two buttons: 'Regresar' (Return) and 'Descargar' (Download).

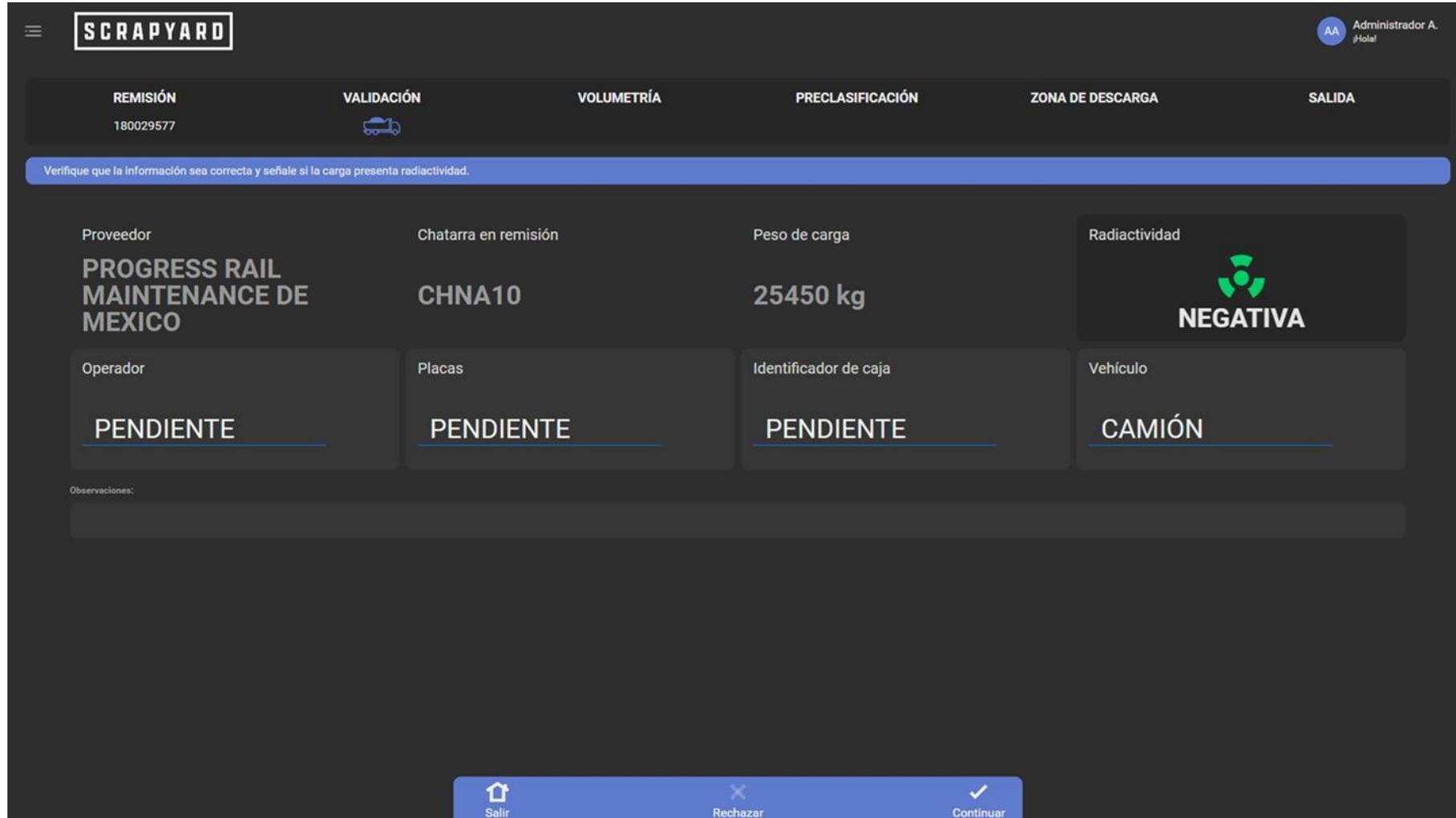
Active workflows

Remisiones activas

REMISIÓN	VALIDACIÓN	VOLUMETRÍA	PRECLASIFICACIÓN	ZONA DE DESCARGA	SALIDA
180047139					
180047133					
24306119135					
24299119115					
24305119101					
180047125					
180047097					
2428517325					

Buscar remisión

Workflow, data validation



SCRAPYARD

Administrador A. (Hola)

REMISIÓN 180029577

VALIDACIÓN

VOLUMETRÍA

PRECLASIFICACIÓN

ZONA DE DESCARGA

SALIDA

Verifique que la información sea correcta y señale si la carga presenta radiactividad.

Proveedor
PROGRESS RAIL
MAINTENANCE DE
MEXICO

Chatarra en remisión
CHNA10

Peso de carga
25450 kg

Radiactividad
NEGATIVA

Operador
PENDIENTE

Placas
PENDIENTE

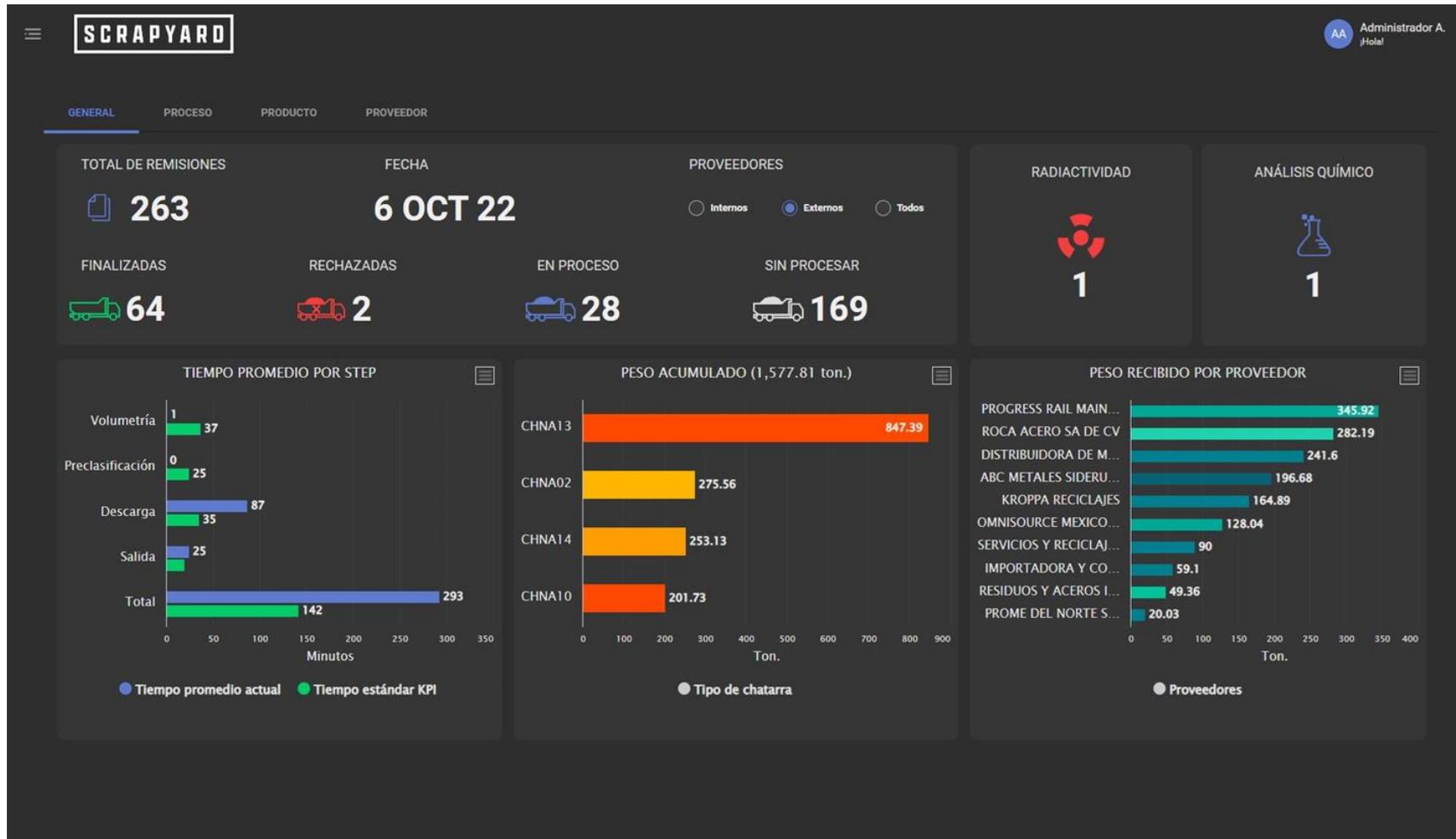
Identificador de caja
PENDIENTE

Vehículo
CAMIÓN

Observaciones:

Salir Rechazar Continuar

Dashboards

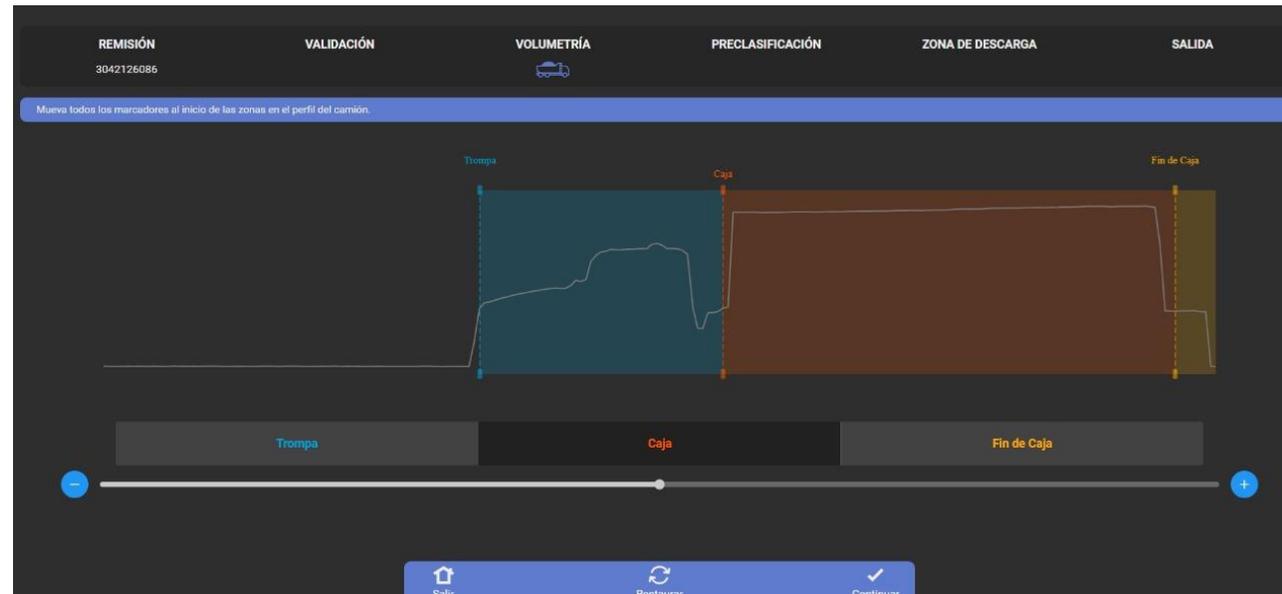


Detection of truck container

Context

SCRAPYARD[®] is an application that automates the processes in scrap handling, specifically one of these processes is obtaining information from the trucks that transport scrap.

The main interest is to determine the start and end of the truck container (markers).



Motivations & Objective

Motivations.

- Reduce human intervention in SCRAPYARD[®] application.
- Automate the acquisition of markers that indicate the start and end of the truck container.

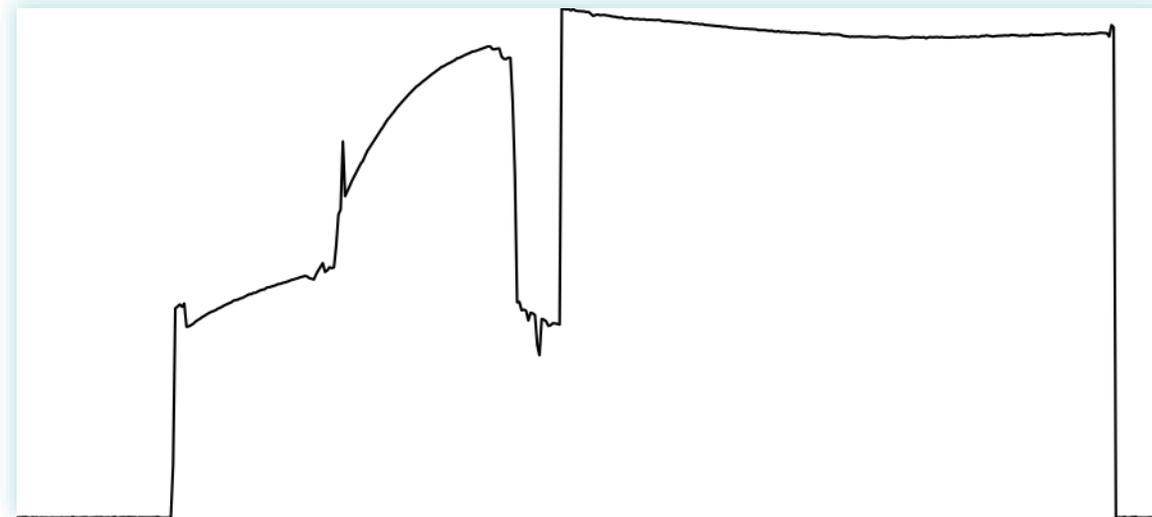
Objective.

- Predict truck container start and end markers using computer vision models specifically a detection model.

Technical Approach

Get data.

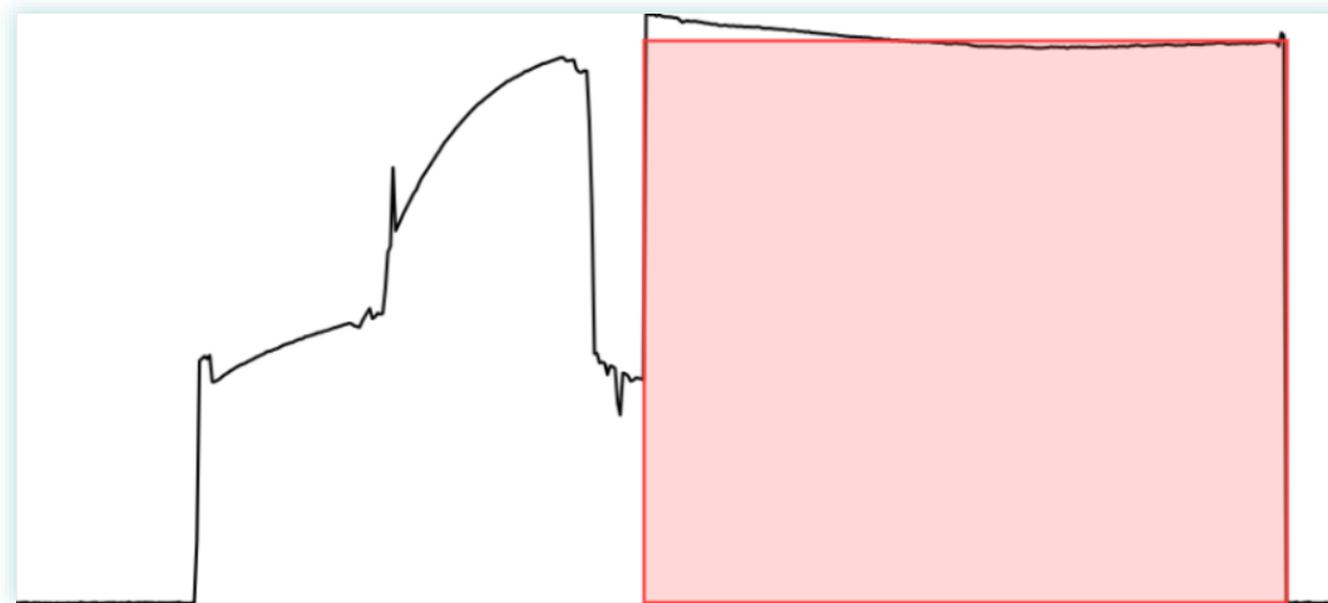
In SCRAPYARD[®], the information of the truck profile obtained by means of a LIDAR sensor is stored with this data we can get the dataset.



Example of truck profile
image

Modeling

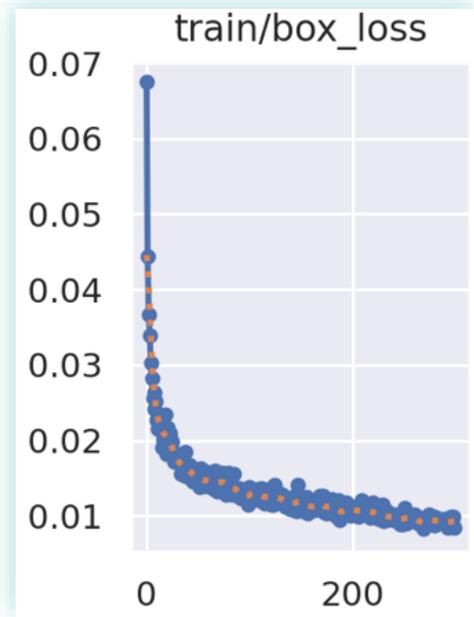
- The dataset collected was split into training, testing and validation subsets.
- A detection model was trained to predict the location of the truck container.



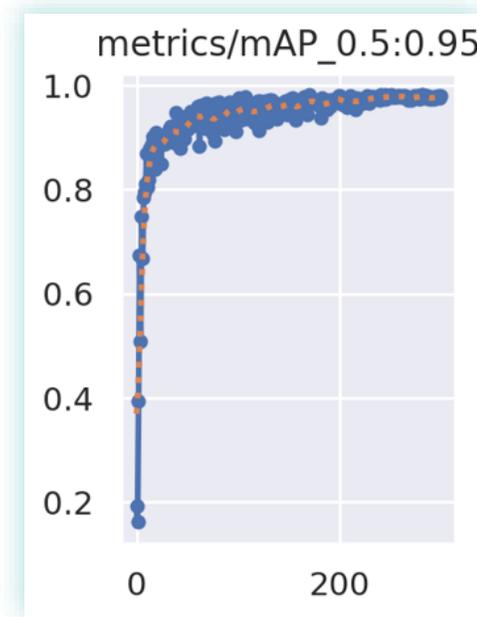
Example of labeling

Results

Training metrics.



Loss function from training



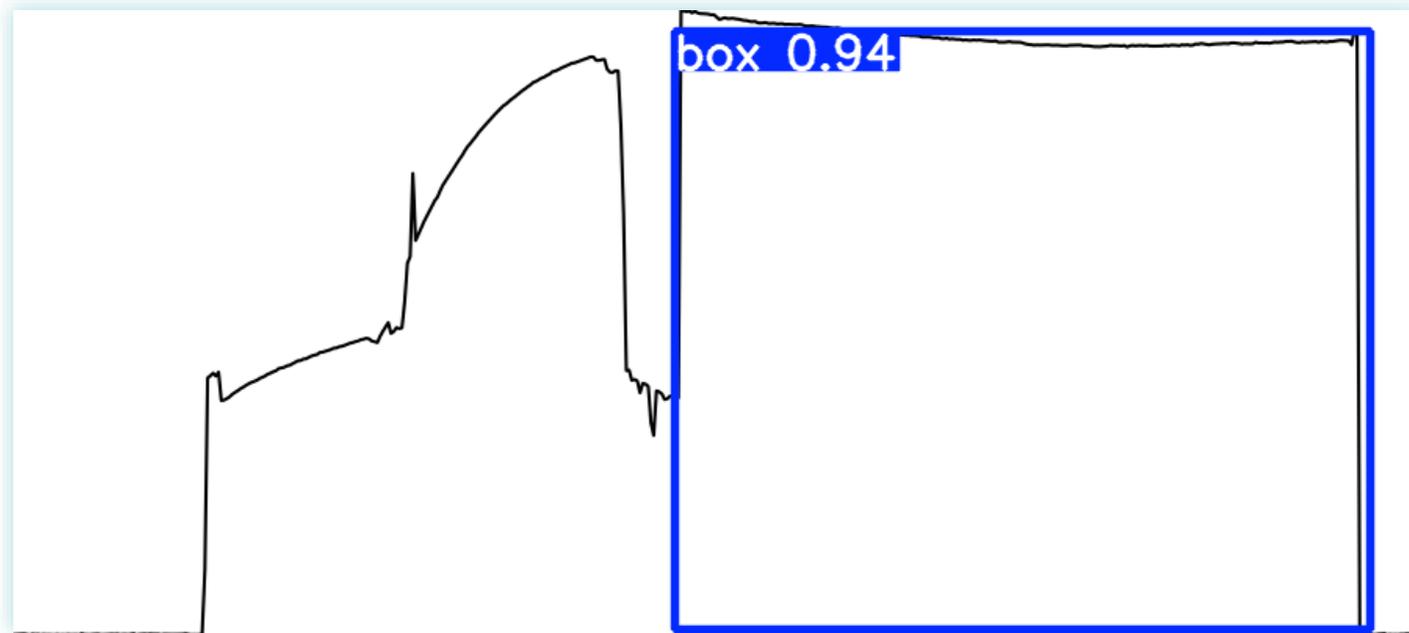
mAP (mean average precision)
metric values during training

Box Loss: Measures how far off the predicted bounding boxes are from the actual object locations.

mAP: Tells how well the model detects and correctly classifies objects by averaging its accuracy across different difficulty levels.

Results

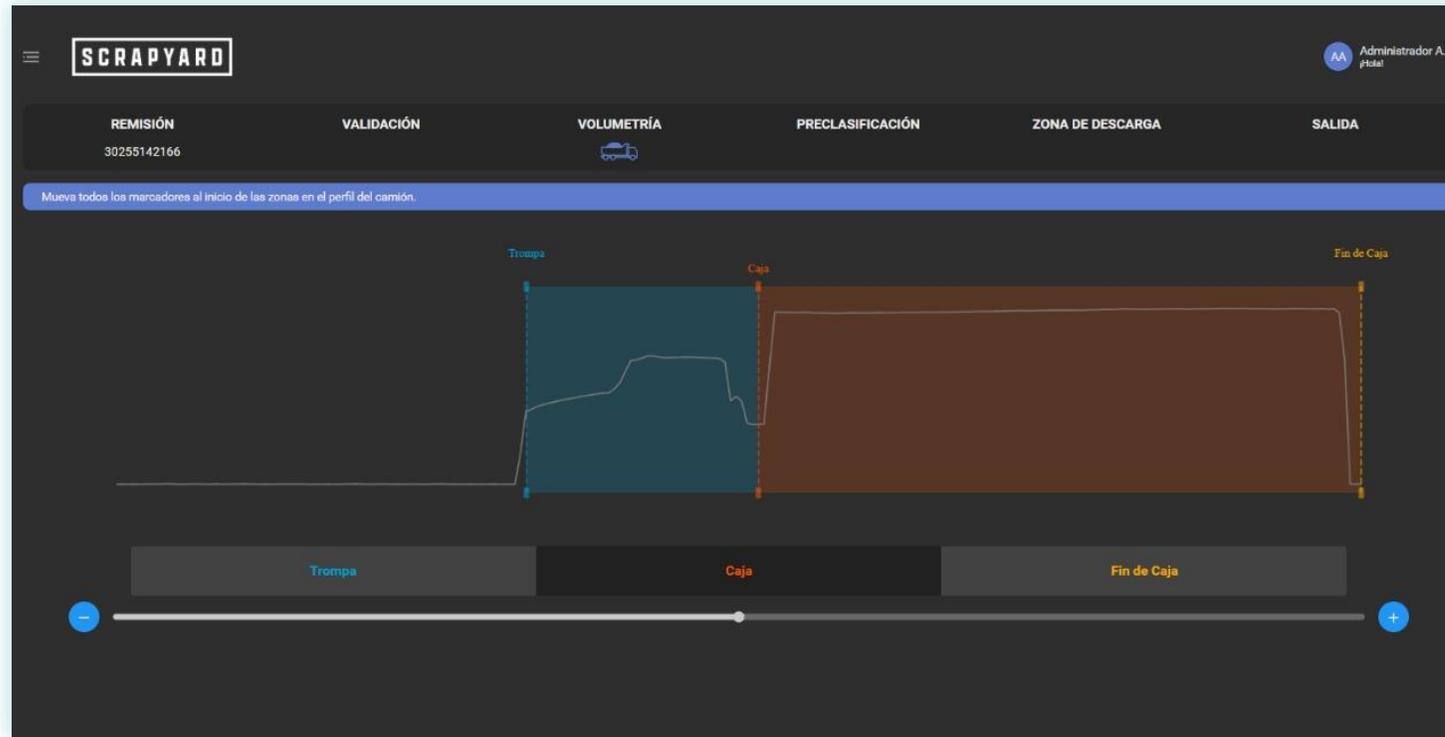
The model achieves **96% accuracy** in detecting the truck container.



Example of model predictions

Determine truck container markers

With the model predictions it is possible to obtain and locate the truck markers in SCRAPYARD[®].



Example of the location of the markers for the truck container in SCRAPYARD[®]

Conclusions

- To address the issue of predicting truck container markers, we decided to use a detection model that showed acceptable results.
- The accuracy of the model in detecting the truck container is 96%.
- Determining the location of the markers helps calculate the volume of the truck container.
- The purpose of reducing human intervention in the location of the markers is achieved.

Detection of hazardous objects

Context

SCRAPYARD[®] functions include the detection of potentially dangerous objects within recycled material.

The aim is to identify these objects before they reach the smelting furnace, where they could pose a significant risk, such as explosions or damage to equipment due to the high temperature of the process. To do this, a detection model based on artificial intelligence has been developed.

Motivations & Objective

Motivations.

- Remove dangerous objects before they reach the furnace.
- Tecnoap, through its SCRAPYARD[®] platform, seeks to reduce the risks of loss of human life or material in the process of scrap entering steel plants.

Objective.

- Identify and classify potentially dangerous objects in the scrap using computer vision models, specifically a detection model.

Modeling

Step 1: Data Collection

Images are gathered from real scrap processing environments to create a representative dataset.

Step 2: Data Processing

Each image is labeled to mark hazardous objects, ensuring the model learns to recognize them accurately.

Step 3: Model Training

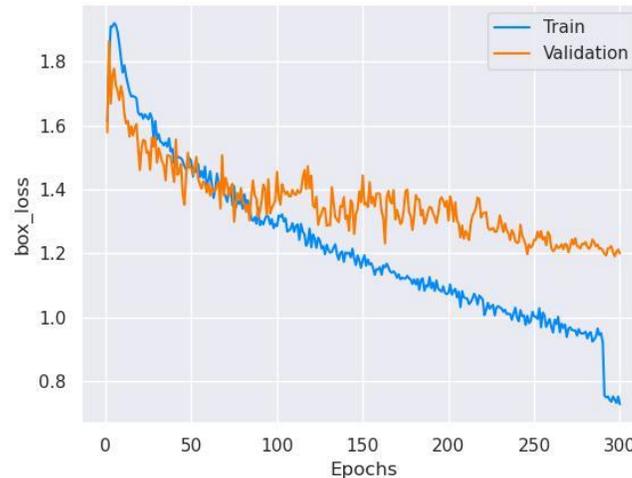
A model is trained using the annotated data to detect and classify potential risks.

Step 4: Real-Time Implementation

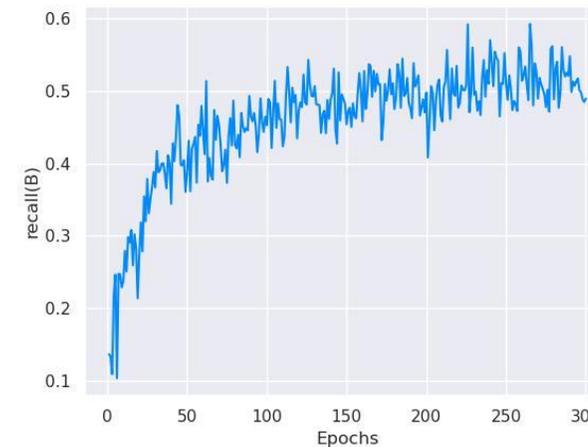
The trained model is deployed in an industrial environment, identifying hazardous objects before they reach the furnace.

Results

Training metrics.



Loss function from training



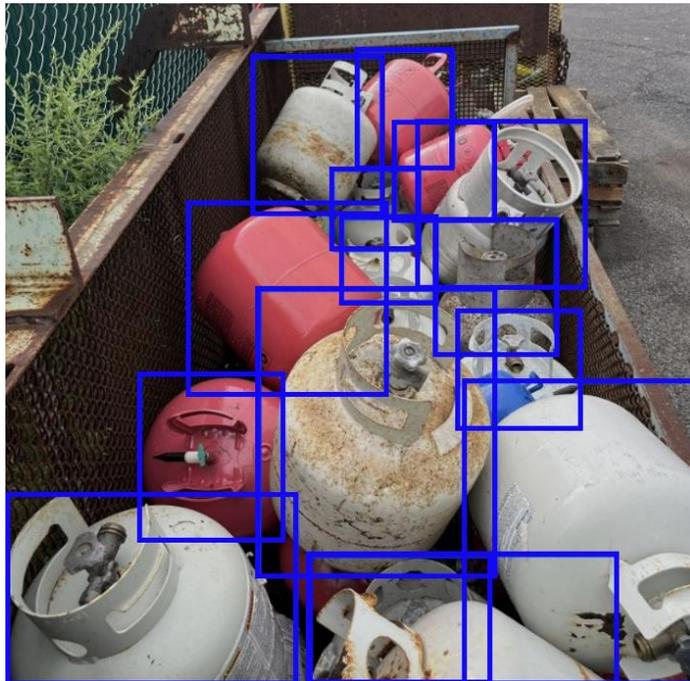
Recall metric values during training

Box Loss: Measures how far off the predicted bounding boxes are from the actual object locations.

Recall: Tells how well the model identifies all relevant objects in the images by measuring the proportion of actual positives (true objects) that the model successfully detects. A higher recall means fewer false negatives, indicating that the model is good at detecting most of the relevant objects.

Results

The model achieves **76% recall** in detecting dangerous objects.



Example of model predictions

Results



Example of model prediction

Conclusions

- To address the problem of detecting dangerous objects in the scrapyards, we implemented an object detection model that has made significant progress in its development. Achieving 76% in recall.
- These results show an improvement in the model's ability to identify dangerous objects, contributing to a safer environment by reducing the risk of accidents.
- The performance of the model plays a crucial role in minimizing manual inspections, making the operation more efficient and safer.

Scrap characterization

Context

SCRAPYARD[®] requires the functionality to analyze scrap transported by trucks in order to establish strategies for scrap management.

The main interest is detecting large objects in the scrap metal.



Example of scrap

Motivations & Objective

Motivations.

- Establish strategies that optimize scrap management.
- Perform the dimensional characterization of scrap automatically.

Objective.

- Locate large objects using a segmentation model.

Technical Approach

Get data.

SCRAPYARD[®] stores images of trucks that transport scrap with this images we can get the dataset.



Example of truck with scap

Modeling

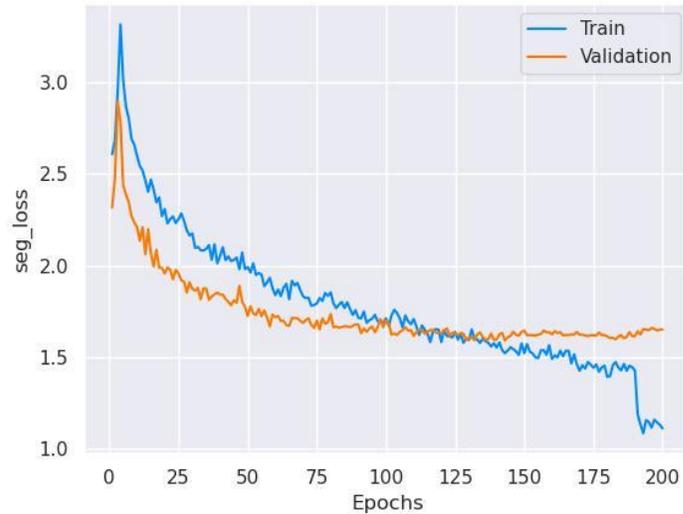
- Each of the images in the database was labeled, that is, identify the different scrap objects.
- A segmentation model was trained to detect the scrap objects.



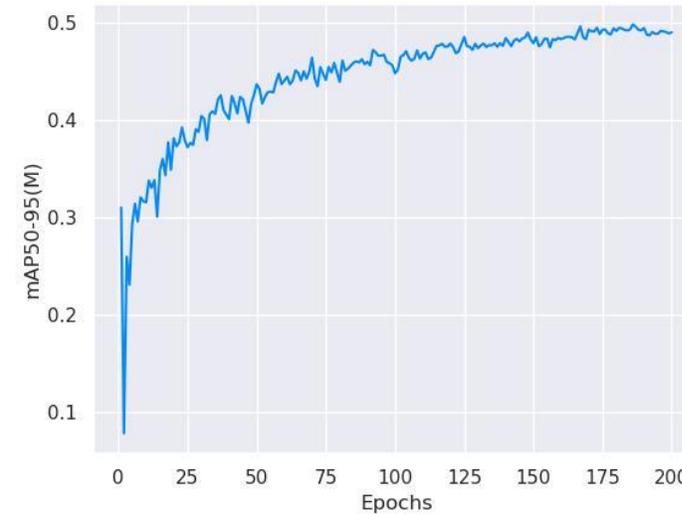
Example of labeling

Results

Training metrics.



Loss segmentation function
from training



mAP (mean average precision)
metric values during training

Segmentation Loss: Measures how far off the predicted segments are from the actual object regions.

mAP: Tells how well the model detects and correctly classifies objects by averaging its accuracy across different difficulty levels.

Results

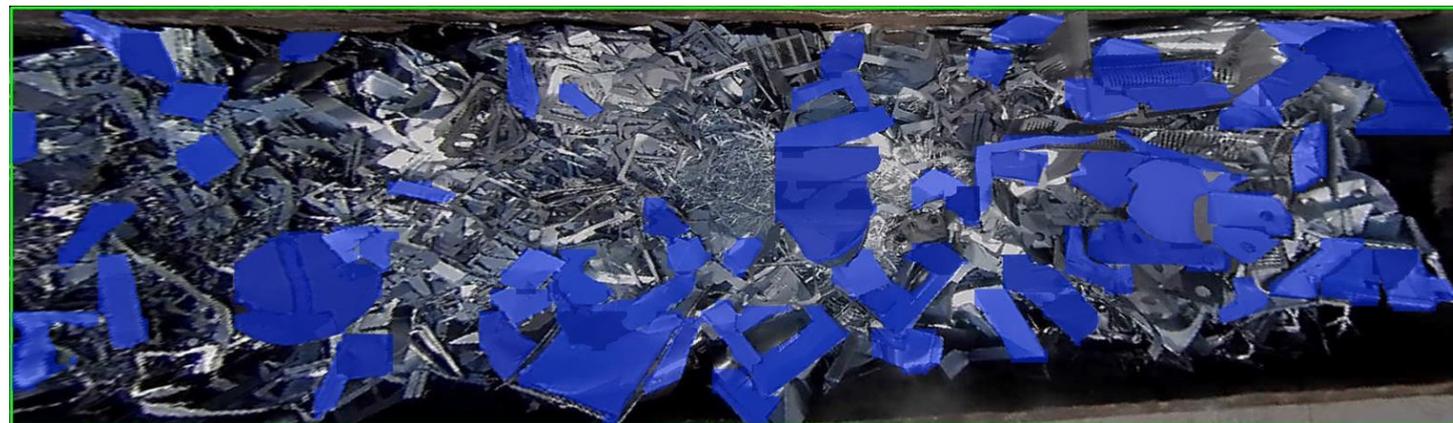
The model achieves **0.55** in mAP metric for test subset.



Example of model predictions

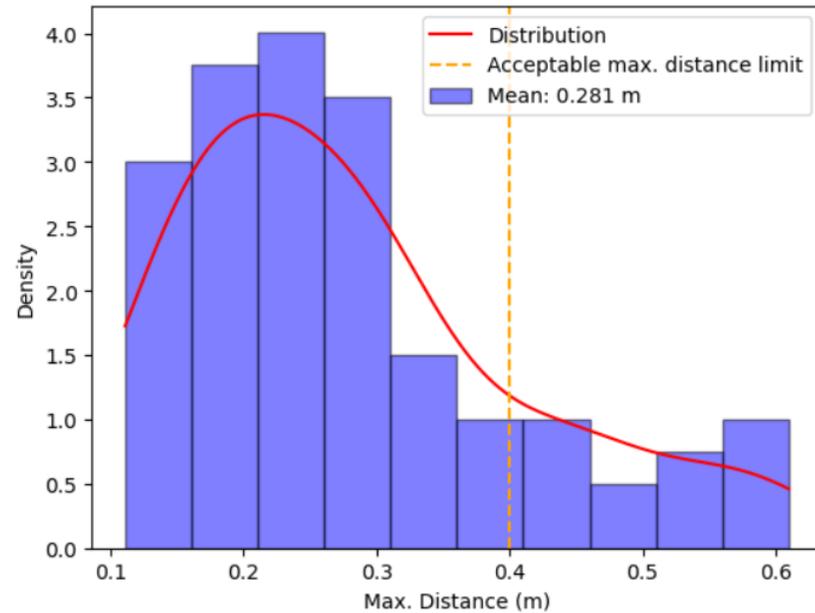
*The value of the mAP metric should be close to 1.

Model predictions



Results

Detect large objects.



*The maximum distance is the largest length that an object can have, measured between two points on its edge; it is equivalent to the longest diagonal that can be drawn.

Conclusions

- A segmentation model is suitable for analyzing the different objects in an image.
- It is possible to obtain a dimensional characterization of the scrap with the predictions of segmentation model.
- The KPI used to detect large objects is the maximum distance.

Conclusions, Business benefits

Reduce uncertainty and variability in classification.

Streamline the process of scrap metal intake.

To reduce possible fraud in the entry of scrap metal.

Strengthen the human expertise of supervisors.

Real-time tracking of incoming scrap.

Information integrity between different departments and systems.

Agility and assertiveness in the audit process.

Improve operational safety.

Minimize controversies about scrap quality.

Assertiveness and reliability in payments to suppliers.

Visibility and control over critical scrap characteristics.

Increase productivity and process efficiency.



Questions?

Thanks!

Contacto

Estados Unidos

2100 West Loop South,
Suite 900

Houston, Texas 77027

+1 (713) 595 3000

México

Francisco Garza Sada, Col.
Chepevera.

Monterrey, Nuevo León,
C.P. 64030

+52 (81) 1934-5590

ventasmx@tecnoap.com

Argentina

Calle 126 No.1370 piso 1-1

Berisso, Buenos Aires

+54 (221) 448-0314

ventas@tecnoap.com

Brasil

2100 West Loop South
Suite #900

Houston, TX. C.P. 77027

+1 (832) 730-1919

www.tecnoap.com · contacto@tecnoap.com